



Geometric and Numerical Foundations of Movements /

Laumond, Jean-Paul
Mansard, Nicolas
Lasserre, Jean-Bernard

Springer International Publishing :
Springer,
2017

Libros electrónicos

Recursos electrónicos

Monografía

This book aims at gathering roboticists, control theorists, neuroscientists, and mathematicians, in order to promote a multidisciplinary research on movement analysis. It follows the workshop 'Geometric and Numerical Foundations of Movements' held at LAAS-CNRS in Toulouse in November 2015[1]. Its objective is to lay the foundations for a mutual understanding that is essential for synergetic development in motion research. In particular, the book promotes applications to robotics --and control in general-- of new optimization techniques based on recent results from real algebraic geometry

<https://rebiunoda.pro.baratznet.cloud:38443/OpacDiscovery/public/catalog/detail/b2FpOmNlbGVicmF0aW9uOmVzLmJhcmF0ei5yZW4vMTg5NjA5Mzk>

Título: Geometric and Numerical Foundations of Movements edited by Jean-Paul Laumond, Nicolas Mansard, Jean-Bernard Lasserre

Editorial: Cham Springer International Publishing Springer 2017

Descripción física: 1 recurso en línea X, 419 p. 106 il

Mención de serie: Springer eBooks Springer Tracts in Advanced Robotics 1610-7438 117

Detalles del sistema: Modo de acceso: World Wide Web

ISBN: 9783319515472 978-3-319-51547-2

Materia: Engineering Neurosciences Numerical analysis Artificial intelligence Geometry Robotics Automation Engineering Robotics and Automation Artificial Intelligence (incl. Robotics) Geometry Neurosciences Numeric Computing Ingeniería

Autores: Laumond, Jean-Paul Mansard, Nicolas Lasserre, Jean-Bernard

Entidades: SpringerLink (Servicio en línea)

- Gran Vía, 59 28013 Madrid
- (+34) 91 456 03 60
- informa@baratz.es